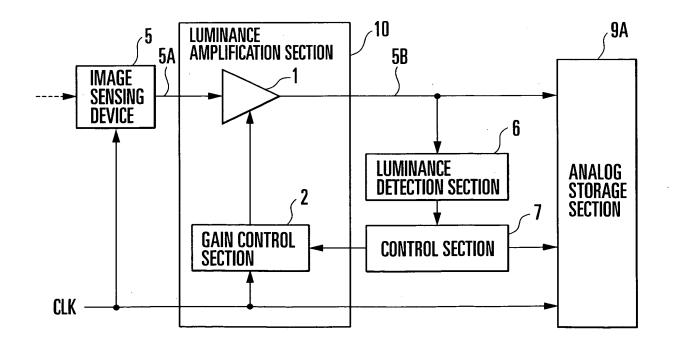
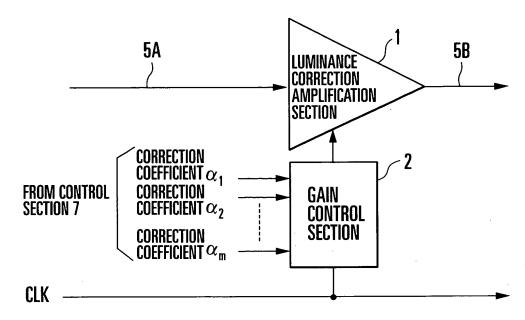


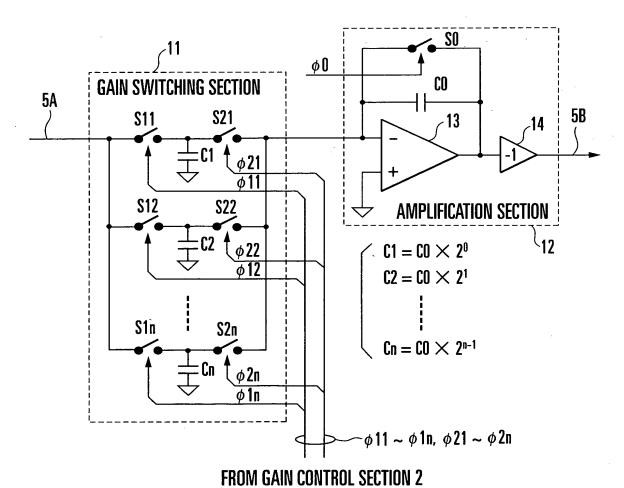
FIG.1A



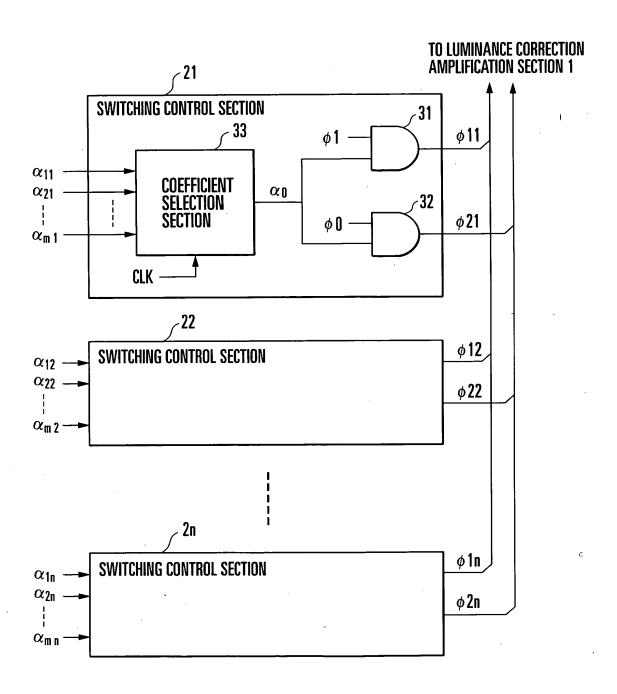
F I G. 1 B



F I G. 2



F I G. 3



F I G. 4

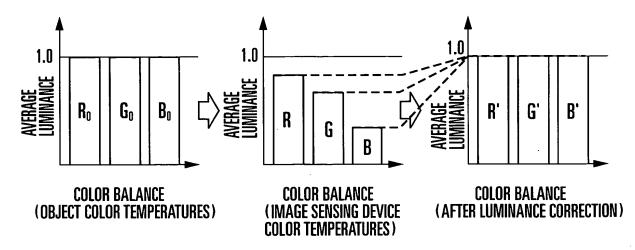


FIG.5A

FIG.5B

FIG.5C

$$\begin{cases}
R' = \alpha_R \times R \\
G' = \alpha_G \times G \\
B' = \alpha_B \times B
\end{cases}$$

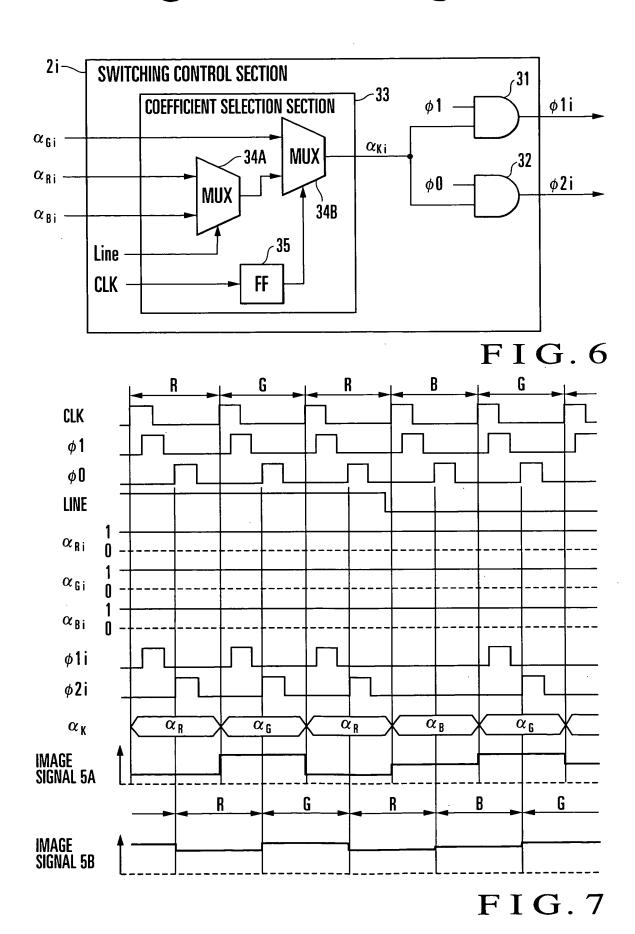
FIG.5D

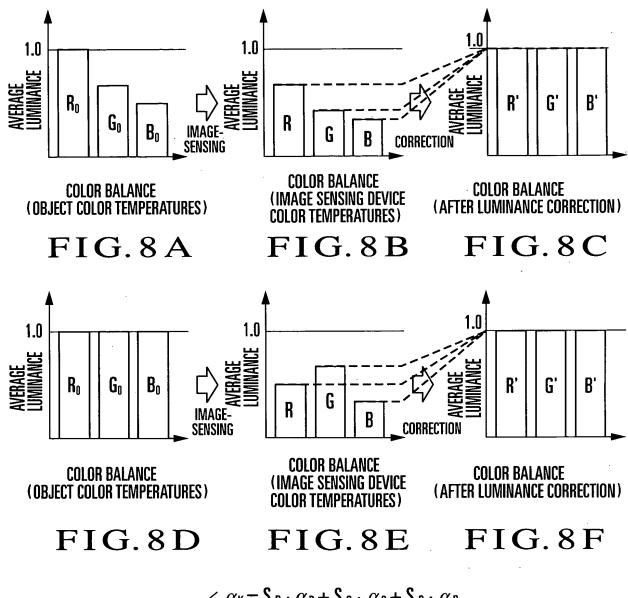
G	R	G	R	G	R	 G	R
В	G	В	G	В	G	 В	G
G	R	G	R	G	R	 G	R
n	_	n	_	n	6		_

FIG.5E

α_{G}	α_{R}	α_{G}	α_{R}	$\alpha_{ extsf{G}}$	α_{R}	 α_{G}	α_{R}
α_B	lpha G	α_{B}	lpha G	$\alpha_{{B}}$	α_{G}	 α_{B}	lpha G
α_{G}	α_{R}	α_{G}	α_{R}	$\alpha_{ m G}$	α_{R}	 α_{G}	α_{R}
لمم	αc	αn	αc	αn	αc		L

FIG.5F





$$\begin{cases} \alpha_{K} = S_{B} \cdot \alpha_{B} + S_{G} \cdot \alpha_{G} + S_{B} \cdot \alpha_{B} \\ S_{B} + S_{G} + S_{B} = 1 \\ S_{B} = \{0, 1\} \\ S_{G} = \{0, 1\} \\ S_{B} = \{0, 1\} \end{cases}$$

$$FIG.8G$$

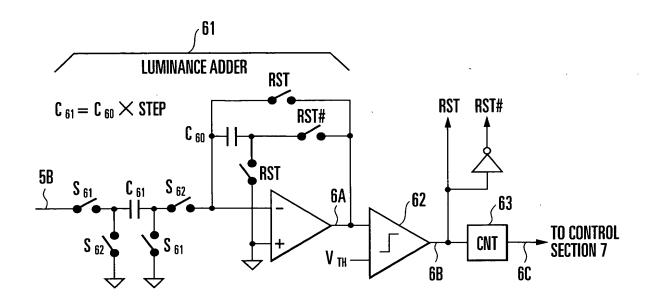


FIG.9A

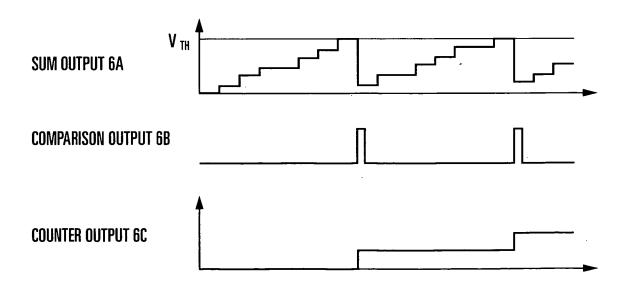
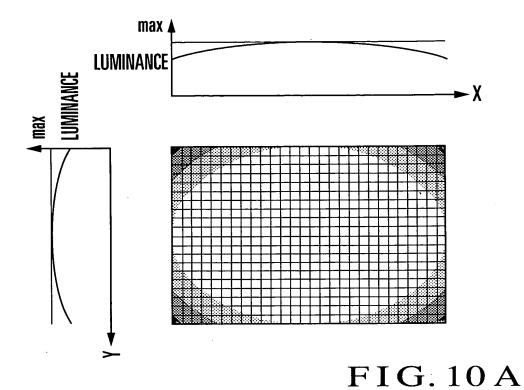


FIG.9B



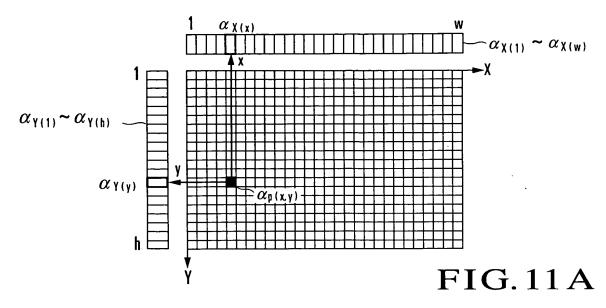
DISTANCE D

DISTANCE L

POINT P

TWO-DIMENSIONAL IMAGE SENSING DEVICE

FIG. 10 B



$$\begin{cases} \alpha_{\mathfrak{p}(x,y)} = \alpha_{\chi(x)} \times \alpha_{\gamma(y)} \\ = \alpha_{\chi(x)} + \alpha_{\gamma(y)} \\ \therefore \alpha_{\chi(x)} = 1, \ \alpha_{\gamma(y)} = 1 \end{cases}$$

FIG.11B

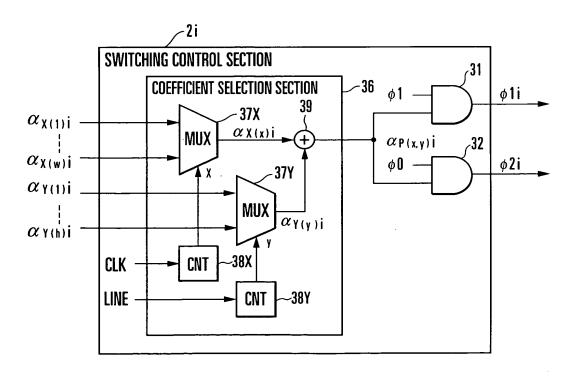


FIG. 12

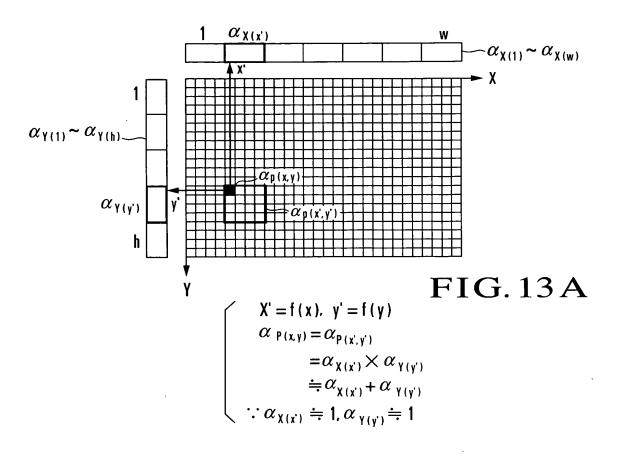


FIG. 13B

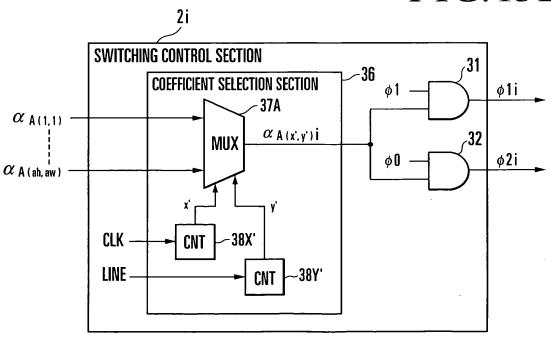


FIG. 14

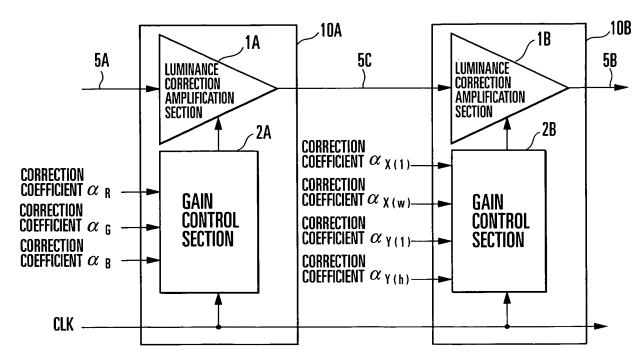


FIG. 15A

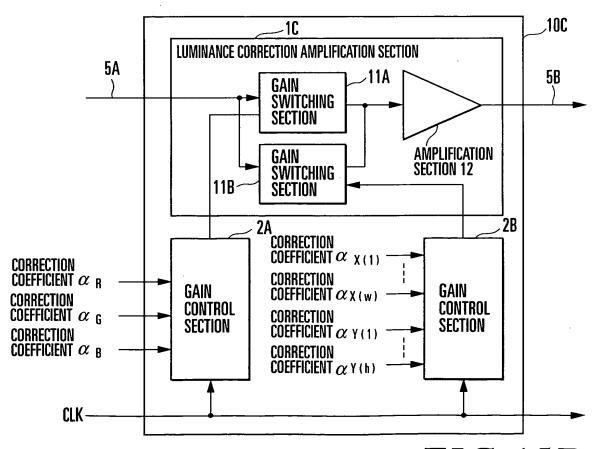


FIG. 15B

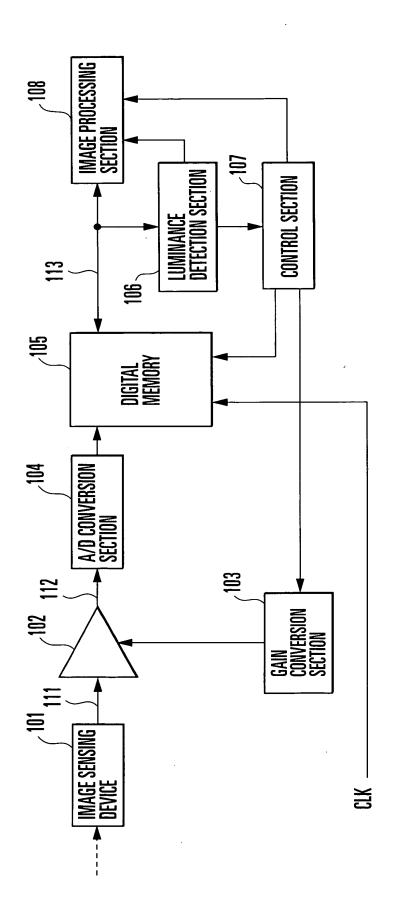


FIG. 16

